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Problem 2. Given: a system with
dynamics $\dot{y} + 2.8\ddot{y} + 0.9 = 0.5u$ and
control law $u = K(Y_{des} - y) + K_d(\dot{y}_{des} - \dot{y})$
Determine: approximate control gains,

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K, and K (i.e. using approximate requirements for the step response characteristics), such that 1. the closed-loop is stable 2. with unit step response requirements: a) $\zeta < 0.65$ b) $|e| < 1\%$ c) no overshoot

Solved: Problem 2. Given: A System With Dynamics $\dot{y} + 2.8\ddot{y} \dots$

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