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description of the theory, methodology, and practice of System Identification. This completely revised Second Edition introduces subspace methods, methods that utilize frequency domain data, and general non-linear black box methods, including neural networks and neuro-fuzzy modeling.

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theoretical foundation
and emphasizing the
practical aspects of the
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that face the user.

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Lennart Ljung was responsible for several of these

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1965, Ho and Kalman (1965) provided a first solution to a challenging system theoretical problem that became known as the state-space realization problem. It can be stated as follows. Construct a minimal state-space realization

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Article (PDF Available)

in IEEE Robotics &

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Manual System identification is an iterative process that includes acquiring, formatting, processing, and identifying raw data from a real-world system based on a mathematical model you select.

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1999) [On the Shelf]

Abstract: Roboticists

are increasingly dealing with challenging complex problems in system identification for model-based control, and this book lays a foundation of knowledge for the reader to absorb, which can help address the said challenges.

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Yu Zhang, Bo Wang,
Xinjing Huang, Online
Optimization of Heated-
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of Pipeline Systems
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Practice, 10.1061/(ASC
E)PS.1949-1204.00004
21, 11, 1, (04019040),
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Bibliography 16 part i:

systems and models 2

Time-Invariant Linear

Systems 18 2.1

Impulse Responses,

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For such non-linear systems, a good choice is system identification in frequency domain.

However, most of the techniques are manual

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and are inappropriate for determination of system parameters.

Frequency domain system identification using arbitrary signals

L. Ljung, System Identification: Theory for the User, 2nd ed., Prentice Hall, 1999.

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(1974). Since then

some ten books and

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papers have appeared

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Especially, the books of

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